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Solution 7

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Question 1: Interpolation conserving three moments

We wish to solve the following system for w_1 , w_2 and w_3 :

$$\begin{aligned} w_1 + w_2 + w_3 &= w_p, \\ w_1 x_1 + w_2 x_2 + w_3 x_3 &= w_p x_p, \\ w_1 x_1^2 + w_2 x_2^2 + w_3 x_3^2 &= w_p x_p^2. \end{aligned} \tag{1}$$

Taking into account the constant grid spacing we get:

$$w_1 + w_2 + w_3 = w_p, \tag{2}$$

$$w_1 (x_2 - h) + w_2 x_2 + w_3 (x_2 + h) = w_p x_p, \tag{3}$$

$$w_1 (x_2 - h)^2 + w_2 x_2^2 + w_3 (x_2 + h)^2 = w_p x_p^2. \tag{4}$$

We first use Eq. 2 to simplify Eq. 3 as follows:

$$\begin{aligned} w_p x_p &= (w_1 + w_2 + w_3) x_2 + w_3 h - w_1 h \\ &= w_p x_2 + w_3 h - w_1 h, \\ w_p (x_p - x_2) &= (w_3 - w_1) h. \end{aligned} \tag{5}$$

Then we use Eq. 5 and Eq. 2 to simplify Eq. 4:

$$\begin{aligned} w_p x_p^2 &= w_1 (x_2 - h)^2 + w_2 x_2^2 + w_3 (x_2 + h)^2 \\ &= w_1 (x_2^2 + h^2 - 2x_2 h) + w_2 x_2^2 + w_3 (x_2^2 + h^2 + 2x_2 h) \\ &= (w_1 + w_2 + w_3) x_2^2 + (w_1 + w_3) h^2 + (w_3 - w_1) 2x_2 h \\ &= (w_1 + w_2 + w_3) x_2^2 + 2w_1 h^2 + (w_3 - w_1) h^2 + (w_3 - w_1) 2x_2 h \\ &= w_p x_2^2 + 2w_1 h^2 + w_p (x_p - x_2)(h + 2x_2), \\ 2w_1 h^2 &= w_p (x_p^2 - x_2^2 - (x_p - x_2)(h + 2x_2)) \\ &= w_p ((x_p - x_2)(x_p + x_2) - (x_p - x_2)(h + 2x_2)) \\ &= w_p (x_p - x_2)(x_p + x_2 - h - 2x_2) \\ &= w_p (x_p - x_2)(x_p - x_2 - h), \\ w_1 &= \frac{1}{2} w_p \lambda (\lambda - 1), \end{aligned} \tag{6}$$

where we used $\lambda = (x_p - x_2)/h$. We can now insert Eq. 6 into Eq. 5 to get:

$$\begin{aligned}
w_p(x_p - x_2) &= (w_3 - w_1)h, \\
w_p \lambda &= w_3 - w_1 \\
&= w_3 - \frac{1}{2} w_p \lambda (\lambda - 1), \\
w_3 &= w_p \lambda \left(1 + \frac{1}{2} \lambda - \frac{1}{2}\right) \\
&= \frac{1}{2} w_p \lambda (\lambda + 1).
\end{aligned} \tag{7}$$

Finally we insert Eq. 6-7 into Eq. 2 to obtain:

$$\begin{aligned}
w_1 + w_2 + w_3 &= w_p, \\
w_2 &= w_p - \frac{1}{2} w_p \lambda (\lambda - 1) - \frac{1}{2} w_p \lambda (\lambda + 1) \\
&= w_p (1 - \lambda^2).
\end{aligned} \tag{8}$$

In order to get f_0 , f_1 and f_2 , and therefore the Λ_2 kernel, we introduce $\lambda_i = (x_p - x_i)/h$ (i.e. $\lambda_1 = \lambda + 1$, $\lambda_2 = \lambda$ and $\lambda_3 = \lambda - 1$) and write:

$$w_1 = \frac{1}{2} w_p (\lambda_1 - 1) (\lambda_1 - 2), \tag{9}$$

$$w_2 = w_p (1 - \lambda_2^2), \tag{10}$$

$$w_3 = \frac{1}{2} w_p (\lambda_3 + 1) (\lambda_3 + 2), \tag{11}$$

or write w_i as a function of λ_i assuming that x_2 is the closest grid point to x_p (i.e. $\lambda \in [-0.5, 0.5]$) as:

$$w_i = w_p \begin{cases} \frac{1}{2} (\lambda_i - 1) (\lambda_i - 2), & \text{if } 0.5 < \lambda_i \leq 1.5, \\ (1 - \lambda_i^2), & \text{if } -0.5 \leq \lambda_i \leq 0.5, \\ \frac{1}{2} (\lambda_i + 1) (\lambda_i + 2), & \text{if } -1.5 \leq \lambda_i < -0.5, \\ 0, & \text{else.} \end{cases} \tag{12}$$

Question 2: Implement particle to mesh interpolation scheme

Running the complete code with the parameters given, we observe that indeed the 0th, 1st and 2nd moments are conserved while the 3rd is not. The relevant code snippet are listed and commented hereafter.

Λ_2 constructor:

```

1 Lambda2()
2 : support_start(-1), support_end(2), support(support_end-support_start
3   )
4 {
5 }

```

The support of the Λ_2 kernel goes $[-1.5, 1.5]$, thus only three grid points are needed: the one closest to the particle, one to its left and one to its right. The support in index space with respect to the closest mesh point is then $\{-1, 0, 1\}$, and so `support_start` and `support_end`, the loop bounds, are -1 and $+2$ respectively.

Λ_2 kernel:

```

1 double kernel(double x)
2 {
3     // TODO: write kernel for the interpolation
4     double absx = fabs(x);
5
6     if (absx < 1.5 && absx >= .5)
7         return .5*(2.-absx)*(1.-absx);
8     else if (absx < .5)
9         return 1. - absx*absx;
10    else // outside of support
11        return 0.;
12 }

```

Due to the symmetry of the kernel we are able to rewrite the Λ_2 kernel with respect to $|\lambda_i|$:

$$w_i = w_p \begin{cases} \frac{1}{2} (|\lambda_i| - 1) (|\lambda_i| - 2), & \text{if } 0.5 \leq |\lambda_i| < 1.5, \\ (1 - \lambda_i^2), & \text{if } |\lambda_i| < 0.5 \end{cases} \quad (13)$$

Note that the kernel is expressed in function of λ and not the physical distance given by $x_p - x_i$.

Λ_2 p2m:

```

1 // perform 2 dimensional P2M of mass contained in particles to the
  mesh
2 void p2m(vector<Particle>& particles, Grid2D& mesh)
3 {
4     // TODO:
5     // 1. make sure all mesh values are set to 0
6     // 2. for each particle find the closest mesh point indices
7     // 3. compute the weights for the interpolation
8     // 4. perform the P2M operation using the weights
9     const double h = mesh.getH();
10
11    // since we are accumulating, we have to make sure the mesh is
  empty
12    mesh.clear();
13
14    for (int p=0; p<particles.size(); p++)
15    {
16        // find the two closest mesh point indices
17        const double px = particles[p].x/h;
18        const double py = particles[p].y/h;
19        int idx = (px-floor(px))<.5 ? (int)floor(px) : (int)ceil(px);
20        int idy = (py-floor(py))<.5 ? (int)floor(py) : (int)ceil(py);
21
22        // compute weights
23        double wx[support], wy[support];
24        for (int i=support_start; i<support_end; i++)

```

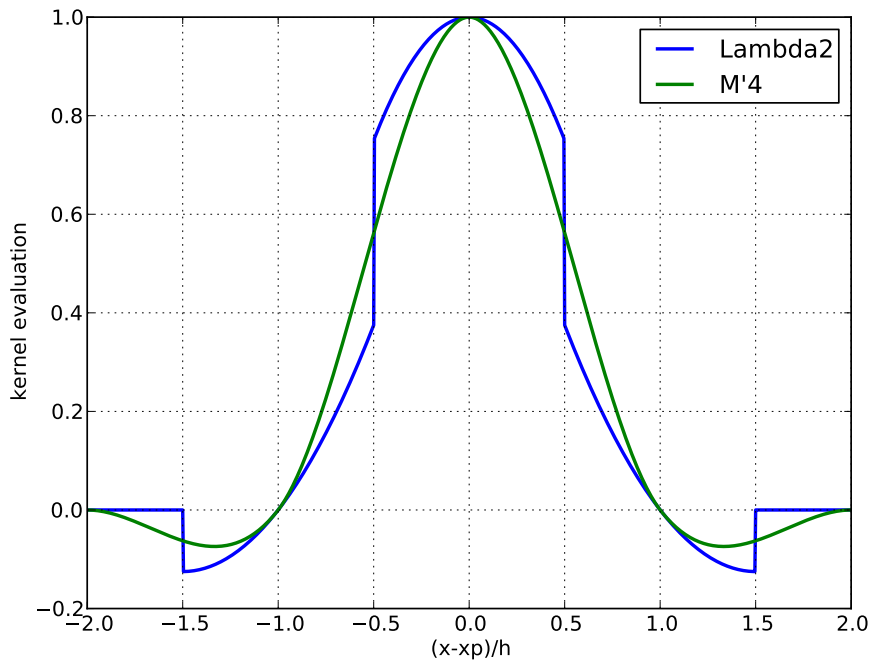
```

25     {
26         wx[i-support_start] = kernel(px-(idx+i));
27         wy[i-support_start] = kernel(py-(idy+i));
28     }
29
30     // distribute mass
31     for (int j=support_start; j<support_end; j++)
32         for (int i=support_start; i<support_end; i++)
33             mesh(idx+i, idy+j) += wx[i-support_start]*wy[j-
34                                     support_start]*particles[p].m;
35 }

```

As the Λ_2 kernel uses an odd number of mesh points, we need to find the closest one and take its two neighbors. The closest point is the one for which $|\lambda_i| < 0.5$, as the next closest one would be at $\lambda_j = 1 - \lambda_i$.

We see that both kernels conserve the 0th, 1st and 2nd moments, whereas the 3rd moment (the last four numbers printed) is not necessarily conserved. The accuracy of the kernels is therefore comparable, and the Λ_2 kernel uses only 3 gridpoints for each particle whereas the M'_4 kernel uses 4. This means the Λ_2 kernel has a significant lower computational cost for the same accuracy, yet in practice the M'_4 kernel is used more frequently. The reason for this is visible when we plot the two kernels:



The Λ_2 kernel, shown with the blue curve, has discontinuities at $(x - x_p)/h = \pm 0.5$ and $(x - x_p)/h = \pm 1.5$, whereas the M'_4 kernel is smooth throughout its support. This smoothness is realized at the cost of an extra point in its support. In a numerical setting, non-smoothness is often avoided because it can cause jumps in a relevant field, which in turn can cause oscillations when, for instance, a high order finite difference scheme is used on the interpolated field. This is an important reason for the popularity of the M'_4 kernel in numerical simulations, even though its usages comes at a higher cost than Λ_2 .