


Introduction

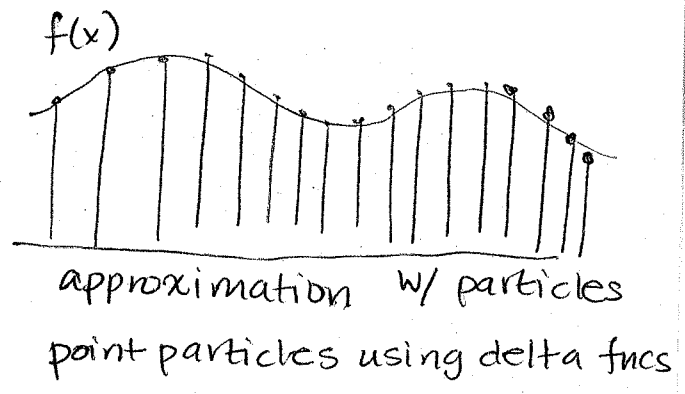
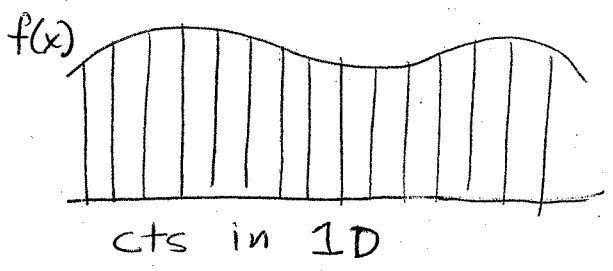
So far we have been talk about discrete particles so far.

- Exs MD
 - bead on a wire
 - planets \rightarrow each planet is particle
 - grains of sand

Now we are going to start talking about modeling cts materials w/ particle methods.

- Exs Fluids (ie a wave, cup of water, flow behind an airplane)
- wire 
- any material that is cts.
- Solids

* In this case must first approximate the continuous material w/ discrete particles.



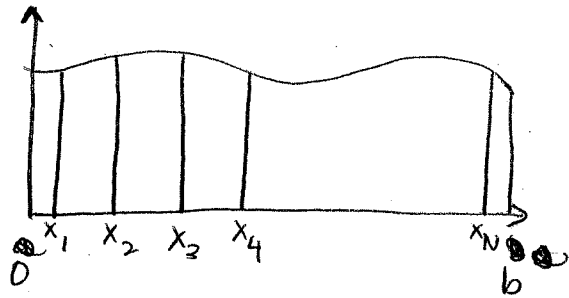
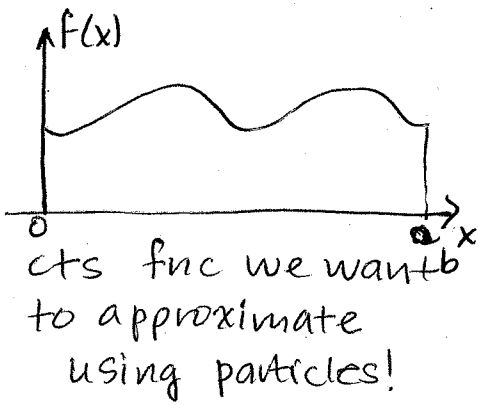
Today Point particles using δ -functions
 δ -functions

~~Discrete Approximations using δ -functions~~

Point Particle Approximations

①

(Work in 1D for now)



$$f(x) \approx f_h(x) = \sum_P f(x_p) h \delta(x - x_p)$$

$$x_p = ph - \frac{h}{2} \quad p = 1, \dots, N$$

$\delta(x - x_p) \rightarrow$ ~~delta~~ delta function

Now we are going to talk about where this comes from and some basics about the delta function.

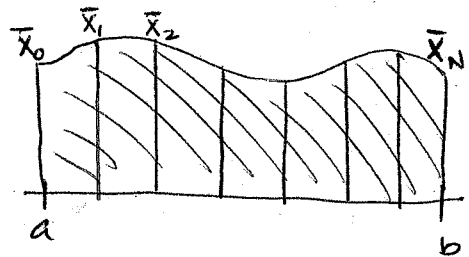
First, Midpoint Rule for Integration

$$\int_a^b g(x) dx = \sum_{p=0}^{N-1} \int_{\bar{x}_p}^{\bar{x}_{p+1}} g(x) dx$$

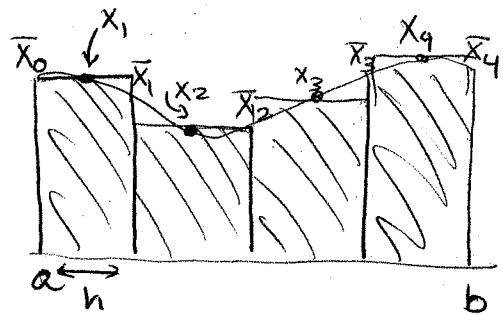
(above $a=0$)

$$\approx \sum_{p=0}^{N-1} g\left(\frac{\bar{x}_p + \bar{x}_{p+1}}{2}\right) h$$

$$= \sum_{p=0}^N g(x_p) h$$



$$(\bar{x}_p = x_p + \frac{1}{2}h)$$



Now the delta function is defined such that

③

$$f(x) = \int_a^b f(y) \delta(x-y) dy$$

* convolution b/n
f and delta function

⇒ if use midpoint rule

$$f(x) = \int_a^b f(y) \delta(x-y) dy$$

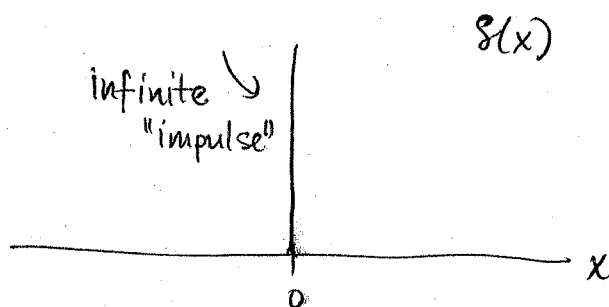
$$\approx \sum_{p=1}^N f(x_p) \delta(x-x_p) h$$

Delta fncs (Dirac Delta function)

Definition is given above:
(convolution)

$$f(x) = \int_a^b f(y) \delta(x-y) dy$$

"function": $\delta(x)$ is infinite at 0
and 0 everywhere else



st $\int_{-\infty}^{\infty} \delta(x) dx = 1$

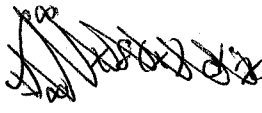
* not really a function (in the strict sense)
since it is nonzero only at one pt and
the untegral is nonzero!

$$\left(\begin{array}{l} \text{ie} \\ f(x) = \begin{cases} 1 & x=0 \\ 0 & x \neq 0 \end{cases} \Rightarrow \int_{\mathbb{R}} f(x) dx = 0 \end{array} \right)$$

moments

Note:

nth moment:



$$\int_{-\infty}^{\infty} x^n \delta(x) dx = 0 \quad \text{for } n \neq 0$$

OR

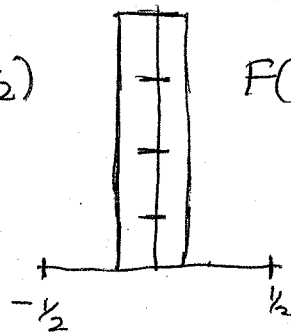
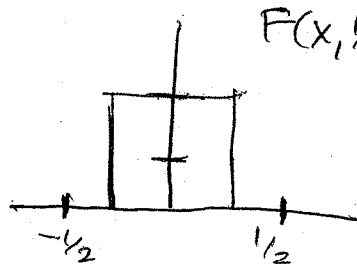
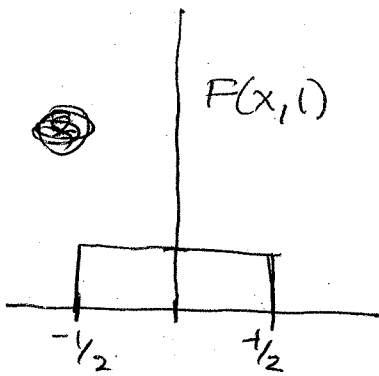
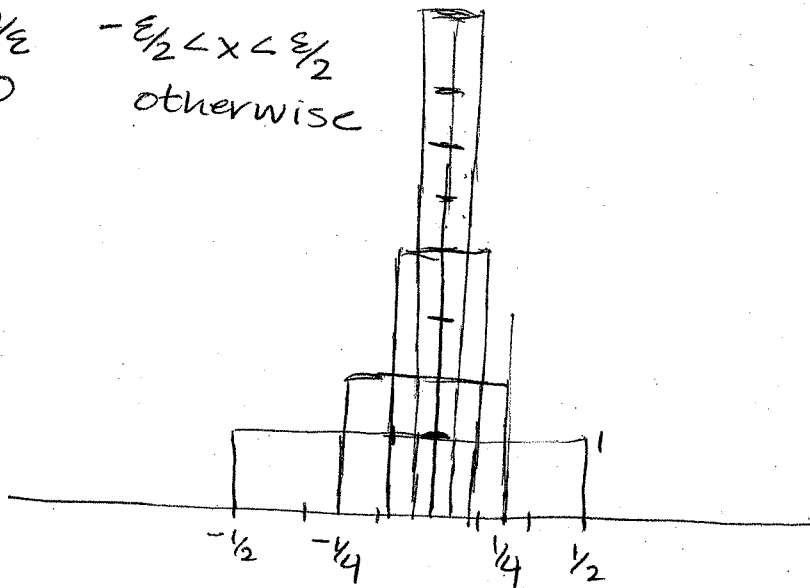
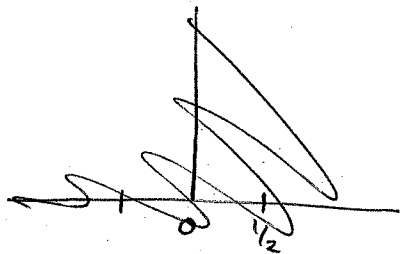
$$\int_{-\infty}^{\infty} (x-y)^n \delta(x) dx = 0 \quad \text{for } n \neq 0$$

Often thought of as a limit of a sequence of functions:

~~Exercises~~

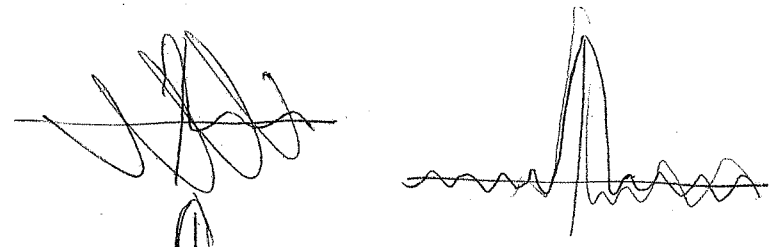
$$\delta(x) = \lim_{\epsilon \rightarrow 0} F(x, \epsilon)$$

Exs ① $F(x, \epsilon) = \begin{cases} 1/2 & -\epsilon/2 < x < \epsilon/2 \\ 0 & \text{otherwise} \end{cases}$

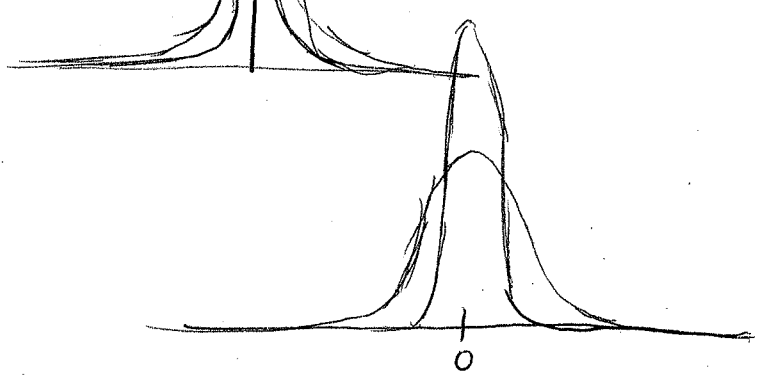
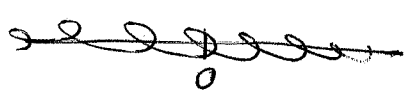


so on

2) $F(x, \epsilon) = \frac{\sin(x/\epsilon)}{\pi x}$



3) $F(x, \epsilon) = \frac{\epsilon/\pi}{x^2 + \epsilon^2}$



4) $F(x, \epsilon) = \frac{1}{2\epsilon} e^{-(x^2/\epsilon^2)}$

(Gaussian) ~~variance~~

(all of these fncs are symmetric but does not have to be).

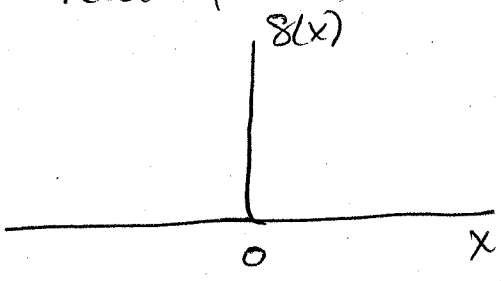
Fourier Transform

$\hat{S}(k) = \int_{-\infty}^{\infty} e^{-2\pi i x k} \delta(x) dx = e^{-2\pi i (0) k} = 1$

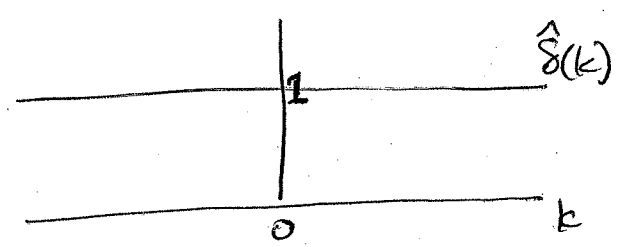
or more generally

$\hat{S}_{x_0}(k) = \int_{-\infty}^{\infty} e^{-2\pi i x k} \delta(x - x_0) dx = e^{-2\pi i x_0 k}$

real space



Fourier space (frequency domain)



constant across all wave #s

Fourier Series (FS)

⑥

Idea write a function (periodic) in terms of sines and cosine

$$f(x) = \sum_{k=-\infty}^{\infty} a_k e^{ikx} \quad \text{where} \quad a_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-ikx} dx$$

⇒ If want FS representation of $g(x)$:

$$\text{Let } f(x) = g(x) \Rightarrow a_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} g(x) e^{ikx} dx = \frac{1}{2\pi}$$

$$\Rightarrow g(x) = \sum_{k=-\infty}^{\infty} \frac{1}{2\pi} e^{ikx}$$

$$\approx \lim_{N \rightarrow \infty} \sum_{k=-N}^N \frac{1}{2\pi} e^{ikx}$$

$$= \lim_{N \rightarrow \infty} \left(1 + e^{ix} + e^{-ix} + \dots + e^{iNx} + e^{-iNx} \right) \frac{1}{2\pi}$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2\pi} \left(1 + e^{ix} + e^{i2x} + \dots + e^{i2Nx} \right) e^{-iNx}$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2\pi} e^{-iNx} \left[\frac{1 - e^{ix(2N+1)}}{1 - e^{ix}} \right] \cdot \frac{e^{-i\frac{1}{2}x}}{e^{-i\frac{1}{2}x}}$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2\pi} \frac{e^{-i(N+\frac{1}{2})x} - e^{i(N+\frac{1}{2})x}}{e^{-i\frac{1}{2}x} - e^{i\frac{1}{2}x}}$$

$$= \lim_{N \rightarrow \infty} \left[\frac{1}{2\pi} \frac{\sin((N+\frac{1}{2})x)}{\sin(\frac{1}{2}x)} \right]^* \quad \text{just another sequence of fncs leading to } g\text{-fnc.}$$

$$\text{(if } x=0 \Rightarrow \lim_{N \rightarrow \infty} \frac{1}{2\pi} (2N+1))$$

* Also, if $\delta(x-x_0) \Rightarrow a_k = \frac{1}{2\pi} e^{-ikx_0}$

and $\delta(x-x_0) = \sum_{k=-\infty}^{\infty} \frac{1}{2\pi} e^{ik(x-x_0)}$

(7)

Higher dimensions:

$\delta(\vec{x}) = \delta(x_1)\delta(x_2)\dots\delta(x_n)$ if $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$

Green's functions and ODEs

A Green's function of a linear differential operator L is defined:

$L[G(x,s)] = \delta(x-s)$ where L is a linear differential operator (in terms of x)

ex) $L = -\frac{d^2}{dx^2} + a^2 \Rightarrow L[G(x,s)] = -\frac{d^2 G(x,s)}{dx^2} + a^2 G(x,s) = \delta(x-s)$

Having the Green's function allows us to solve equations of the type:

$L[u(x)] = f(x)$

since $\int_{-\infty}^{\infty} L[G(x,s)] f(s) ds = \int_{-\infty}^{\infty} \delta(x-s) f(s) ds = f(x)$

$\Rightarrow L[u(x)] = \int_{-\infty}^{\infty} L[G(x,s)] f(s) ds = L \left[\int_{-\infty}^{\infty} G(x,s) f(s) ds \right]$

so $u(x) = \int_{-\infty}^{\infty} G(x,s) f(s) ds$

So in our example:

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need to solve for $G(x,s)$

$$-\frac{d^2 G(x,s)}{dx^2} + a^2 G(x,s) = \delta(x-s)$$

take FT
(in x)

$$-(ik)^2 \hat{G}(k,s) + a^2 \hat{G}(k,s) = \hat{\delta}(k) = e^{-2\pi i s k}$$

take FT
(in x)

$$-(ik)^2 \hat{G}(k,s) + a^2 \hat{G}(k,s) = \hat{\delta}(k) = e^{-2\pi i s k}$$
$$\hat{G}(k,s) \cdot (-ik)^2 + a^2 = e^{-2\pi i s k}$$
$$\hat{G}(k,s) = \frac{e^{-2\pi i s k}}{-(-ik)^2 + a^2}$$

\Rightarrow just take inverse FT to get $G(x,s)$

~~$G(x,s)$~~

\Rightarrow can solve $\frac{d^2 G(x,s)}{dx^2} + a^2 G(x,s) = f(x)$

$$\frac{d^2 u(x)}{dx^2} + a^2 u(x) = f(x)$$

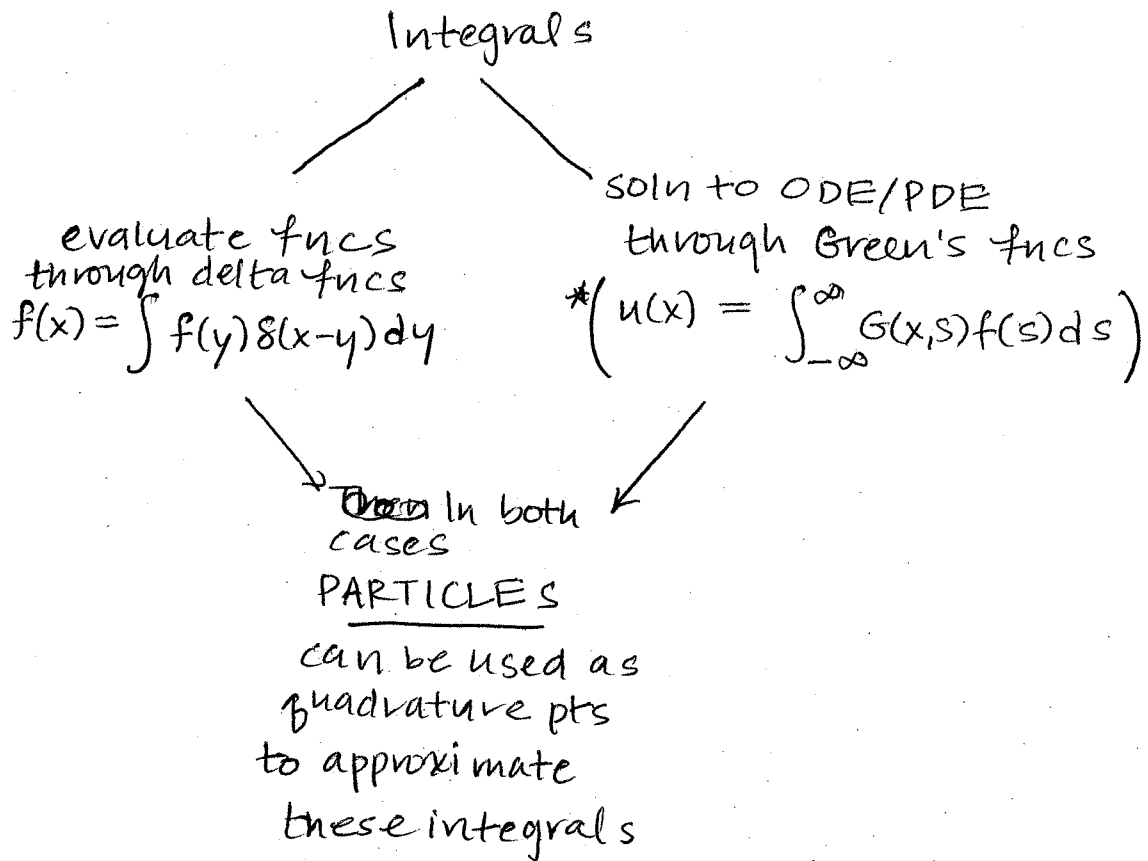
$$\text{as } u(x) = \int_{-\infty}^{\infty} G(x,s) f(s) ds$$

⇒ Approximations using Particles:

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$$u(x) \approx \sum G(x, x_p) f(x_p) h \quad \text{where } h \text{ is mesh size from before.}$$

Summarize



Smooth Approximations to the δ -function

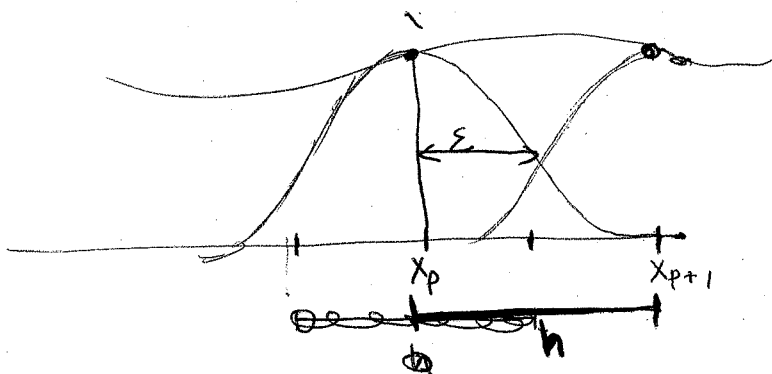
So we have shown

$$f(x) \approx \sum_P f(x_p) h \delta(x-x_p) \quad (\text{in } 1D)$$

Now let $w_p = f(x_p)h \Rightarrow f(x) \approx \sum_{p=1}^N w_p \delta(x-x_p) \equiv f^h(x)$ ~~(in 1D)~~
weights (in 1D)

\Rightarrow we can approximate the $\delta(x-x_p)$ w/ some smooth func ξ_ϵ

$$f(x) \approx f^h(x) \approx f_{\delta h}^\epsilon(x) \equiv \sum_{p=1}^N w_p \xi_\epsilon(x-x_p)$$



Ex $\xi_\epsilon = \xi \left(\frac{\|x\|}{\epsilon^d} \right) \frac{1}{\epsilon^d} = \xi \left(\frac{\|x\|}{\epsilon} \right) \frac{1}{\epsilon}$ $d \rightarrow \text{dim}$

when $d=1$

and let $\xi(x) = \frac{e^{-x^2}}{(\pi/2)}$

$\epsilon \rightarrow$ smoothing length so as $\epsilon \rightarrow 0$ $\xi_\epsilon \rightarrow \delta \Rightarrow$ point particles

(if $d > 1 \Rightarrow f(x) \approx \sum_P \underbrace{f(x_p)h^d}_{w_p} \xi_\epsilon(x-x_p)$)

often h will be called the volume of the particle!

⇒ For smooth particle methods we have 2 length scales: (11)

- ① Volume/distance btu particles
- ② Smoothing Length

Error

$$\begin{aligned} |f(x) - f_\epsilon^h(x)| &= |f(x) - f_\epsilon(x) + f_\epsilon(x) - f_\epsilon^h(x)| \\ &\leq \underbrace{|f(x) - f_\epsilon(x)|}_{\text{① (SMOOTHING) ERROR}} + \underbrace{|f_\epsilon(x) - f_\epsilon^h(x)|}_{\text{② DISCRETIZATION ERROR}} \\ &\quad \text{MOLLIFICATION ERROR} \end{aligned}$$

① Mollification error - related to δ being approximated by ξ_ϵ

$$\left| \int f(y) \delta(x-y) dy - \int f(y) \xi_\epsilon(x-y) dy \right|$$

② Discretization error - error made by quadrature

$$\left| \int f(y) \xi_\epsilon(x-y) dy - \sum_{p=1}^N w_p \xi_\epsilon(x-x_p) \right|$$